

65. The problem asks that we put the origin of coordinates at point  $O$  but compute all the angular momenta and torques relative to point  $A$ . This requires some care in defining  $\vec{r}$  (which occurs in the angular momentum and torque formulas). If  $\vec{r}_O$  locates the point (where the block is) in the prescribed coordinates, and  $\vec{r}_{OA} = -1.2\hat{j}$  points from  $O$  to  $A$ , then  $\vec{r} = \vec{r}_O - \vec{r}_{OA}$  gives the position of the block relative to point  $A$ . SI units are used throughout this problem.

- (a) Here, the momentum is  $\vec{p}_0 = m\vec{v}_0 = 1.5\hat{i}$  and  $\vec{r}_0 = 1.2\hat{j}$ , so that

$$\vec{\ell}_0 = \vec{r}_0 \times \vec{p}_0 = -1.8\hat{k} \text{ kg}\cdot\text{m}^2/\text{s} .$$

- (b) The horizontal component of momentum doesn't change in projectile motion (without friction), and its vertical component depends on how far its fallen. From either the free-fall equations of Ch. 2 or the energy techniques of Ch. 8, we find the vertical momentum component after falling a distance  $h$  to be  $-m\sqrt{2gh}$ . Thus, with  $m = 0.50$  and  $h = 1.2$ , the momentum just before the block hits the floor is  $\vec{p} = 1.5\hat{i} - 2.4\hat{j}$ . Now,  $\vec{r} = R\hat{i}$  where  $R$  is figured from the projectile motion equations of Ch. 4 to be  $R = v_0\sqrt{\frac{2h}{g}} = 1.5 \text{ m}$ . Consequently,

$$\vec{\ell} = \vec{r} \times \vec{p} = -3.6\hat{k} \text{ kg}\cdot\text{m}^2/\text{s} .$$

- (c) and (d) The only force on the object is its weight  $m\vec{g} = -4.9\hat{j}$ . Thus,

$$\begin{aligned} \vec{\tau}_0 &= \vec{r}_0 \times \vec{F} = 0 \\ \vec{\tau} &= \vec{r} \times \vec{F} = -7.3\hat{k} \text{ N}\cdot\text{m} . \end{aligned}$$