

1. (a) The flux through the top is  $+(0.30 \text{ T})\pi r^2$  where  $r = 0.020 \text{ m}$ . The flux through the bottom is  $+0.70 \text{ mWb}$  as given in the problem statement. Since the *net* flux must be zero then the flux through the sides must be negative and exactly cancel the total of the previously mentioned fluxes. Thus (in magnitude) the flux through the sides is  $1.1 \text{ mWb}$ .

(b) The fact that it is negative means it is inward.

2. We use  $\sum_{n=1}^6 \Phi_{Bn} = 0$  to obtain

$$\Phi_{B6} = -\sum_{n=1}^5 \Phi_{Bn} = -(-1 \text{ Wb} + 2 \text{ Wb} - 3 \text{ Wb} + 4 \text{ Wb} - 5 \text{ Wb}) = +3 \text{ Wb} .$$

3. (a) We use Gauss' law for magnetism:  $\oint \vec{B} \cdot d\vec{A} = 0$ . Now,  $\oint \vec{B} \cdot d\vec{A} = \Phi_1 + \Phi_2 + \Phi_C$ , where  $\Phi_1$  is the magnetic flux through the first end mentioned,  $\Phi_2$  is the magnetic flux through the second end mentioned, and  $\Phi_C$  is the magnetic flux through the curved surface. Over the first end the magnetic field is inward, so the flux is  $\Phi_1 = -25.0 \mu\text{Wb}$ . Over the second end the magnetic field is uniform, normal to the surface, and outward, so the flux is  $\Phi_2 = AB = \pi r^2 B$ , where  $A$  is the area of the end and  $r$  is the radius of the cylinder. Its value is

$$\Phi_2 = \pi(0.120\text{ m})^2 (1.60 \times 10^{-3} \text{ T}) = +7.24 \times 10^{-5} \text{ Wb} = +72.4 \mu\text{Wb}.$$

Since the three fluxes must sum to zero,

$$\Phi_C = -\Phi_1 - \Phi_2 = 25.0 \mu\text{Wb} - 72.4 \mu\text{Wb} = -47.4 \mu\text{Wb}.$$

Thus, the magnitude is  $|\Phi_C| = 47.4 \mu\text{Wb}$ .

(b) The minus sign in  $\Phi_C$  indicates that the flux is inward through the curved surface.

4. From Gauss' law for magnetism, the flux through  $S_1$  is equal to that through  $S_2$ , the portion of the  $xz$  plane that lies within the cylinder. Here the normal direction of  $S_2$  is  $+y$ . Therefore,

$$\begin{aligned}\Phi_B(S_1) &= \Phi_B(S_2) = \int_{-r}^r B(x) L \, dx = 2 \int_{-r}^r B_{\text{left}}(x) L \, dx = 2 \int_{-r}^r \frac{\mu_0 i}{2\pi} \frac{1}{2r-x} L \, dx \\ &= \frac{\mu_0 i L}{\pi} \ln 3 .\end{aligned}$$

5. We use the result of part (b) in Sample Problem 32-1:

$$B = \frac{\mu_0 \epsilon_0 R^2}{2r} \frac{dE}{dt} \quad (\text{for } r \geq R)$$

to solve for  $dE/dt$ :

$$\frac{dE}{dt} = \frac{2Br}{\mu_0 \epsilon_0 R^2} = \frac{2(2.0 \times 10^{-7} \text{ T})(6.0 \times 10^{-3} \text{ m})}{(4\pi \times 10^{-7} \text{ T} \cdot \text{m/A})(8.85 \times 10^{-12} \frac{\text{C}^2}{\text{N} \cdot \text{m}^2})(3.0 \times 10^{-3} \text{ m})^2} = 2.4 \times 10^{13} \frac{\text{V}}{\text{m} \cdot \text{s}}.$$

6. From Sample Problem 32-1 we know that  $B \propto r$  for  $r \leq R$  and  $B \propto r^{-1}$  for  $r \geq R$ . So the maximum value of  $B$  occurs at  $r = R$ , and there are two possible values of  $r$  at which the magnetic field is 75% of  $B_{\max}$ . We denote these two values as  $r_1$  and  $r_2$ , where  $r_1 < R$  and  $r_2 > R$ .

(a) Inside the capacitor,  $0.75 B_{\max}/B_{\max} = r_1/R$ , or  $r_1 = 0.75 R = 0.75 (40 \text{ mm}) = 30 \text{ mm}$ .

(b) Outside the capacitor,  $0.75 B_{\max}/B_{\max} = (r_2/R)^{-1}$ , or  $r_2 = R/0.75 = 4R/3 = (4/3)(40 \text{ mm}) = 53 \text{ mm}$ .

(c) From Eqs. 32-15 and 32-17,

$$B_{\max} = \frac{\mu_0 i_d}{2\pi R} = \frac{\mu_0 i}{2\pi R} = \frac{(4\pi \times 10^{-7} \text{ T} \cdot \text{m/A})(6.0 \text{ A})}{2\pi(0.040 \text{ m})} = 3.0 \times 10^{-5} \text{ T}.$$

7. (a) Noting that the magnitude of the electric field (assumed uniform) is given by  $E = V/d$  (where  $d = 5.0$  mm), we use the result of part (a) in Sample Problem 32-1

$$B = \frac{\mu_0 \epsilon_0 r}{2} \frac{dE}{dt} = \frac{\mu_0 \epsilon_0 r}{2d} \frac{dV}{dt} \quad (\text{for } r \leq R).$$

We also use the fact that the time derivative of  $\sin(\omega t)$  (where  $\omega = 2\pi f = 2\pi(60) \approx 377/\text{s}$  in this problem) is  $\omega \cos(\omega t)$ . Thus, we find the magnetic field as a function of  $r$  (for  $r \leq R$ ; note that this neglects “fringing” and related effects at the edges):

$$B = \frac{\mu_0 \epsilon_0 r}{2d} V_{\max} \omega \cos(\omega t) \Rightarrow B_{\max} = \frac{\mu_0 \epsilon_0 r V_{\max} \omega}{2d}$$

where  $V_{\max} = 150$  V. This grows with  $r$  until reaching its highest value at  $r = R = 30$  mm:

$$B_{\max} \Big|_{r=R} = \frac{\mu_0 \epsilon_0 R V_{\max} \omega}{2d} = \frac{(4\pi \times 10^{-7} \text{ H/m})(8.85 \times 10^{-12} \text{ F/m})(30 \times 10^{-3} \text{ m})(150 \text{ V})(377/\text{s})}{2(5.0 \times 10^{-3} \text{ m})}$$

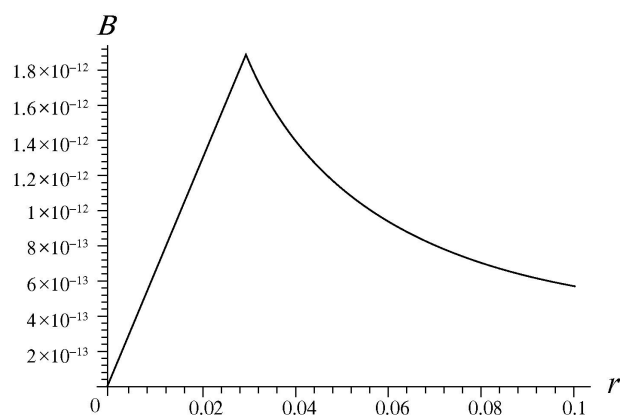
$$= 1.9 \times 10^{-12} \text{ T}.$$

(b) For  $r \leq 0.03$  m, we use the  $B_{\max} = \frac{\mu_0 \epsilon_0 r V_{\max} \omega}{2d}$  expression found in part (a) (note the  $B \propto r$  dependence), and for  $r \geq 0.03$  m we perform a similar calculation starting with the result of part (b) in Sample Problem 32-1:

$$B_{\max} = \left( \frac{\mu_0 \epsilon_0 R^2}{2r} \frac{dE}{dt} \right)_{\max} = \left( \frac{\mu_0 \epsilon_0 R^2}{2rd} \frac{dV}{dt} \right)_{\max} = \left( \frac{\mu_0 \epsilon_0 R^2}{2rd} V_{\max} \omega \cos(\omega t) \right)_{\max}$$

$$= \frac{\mu_0 \epsilon_0 R^2 V_{\max} \omega}{2rd} \quad (\text{for } r \geq R)$$

(note the  $B \propto r^{-1}$  dependence — See also Eqs. 32-16 and 32-17). The plot (with SI units understood) is shown below.





8. (a) Inside we have (by Eq. 32-16)  $B = \mu_0 i_d r_1 / 2\pi R^2$ , where  $r_1 = 0.0200$ ,  $R = 0.0300$ , and the displacement current is given by Eq. 32-38:  $i_d = \epsilon_0 d\Phi_E / dt = \epsilon_0(0.00300)$ , in SI units. Thus we find  $B = 1.18 \times 10^{-19} \text{ T}$ .

(b) Outside we have (by Eq. 32-17)  $B = \mu_0 i_d / 2\pi r_2$  where  $r_2 = 0.0500$  in SI units. Here we obtain  $B = 1.06 \times 10^{-19} \text{ T}$ .

9. (a) Application of Eq. 32-3 along the circle referred to in the second sentence of the problem statement (and taking the derivative of the flux expression given in that sentence) leads to

$$B (2\pi r) = \epsilon_0 \mu_0 (0.60 \text{ V}\cdot\text{m/s}) \frac{r}{R} .$$

Using  $r = 0.0200$  (which, in any case, cancels out) and  $R = 0.0500$  (SI units understood) leads to  $B = 3.54 \times 10^{-17} \text{ T}$ .

(b) For a value of  $r$  larger than  $R$ , we must note that the flux enclosed has already reached its full amount (when  $r = R$  in the given flux expression). Referring to the equation we wrote in our solution of part (a), this means that the final fraction ( $\frac{r}{R}$ ) should be replaced with unity. On the left hand side of that equation, we set  $r = 0.0500 \text{ m}$  and solve. We now find  $B = 2.13 \times 10^{-17} \text{ T}$ .

10. (a) Application of Eq. 32-7 with  $A = \pi r^2$  (and taking the derivative of the field expression given in the problem) leads to

$$B(2\pi r) = \epsilon_0 \mu_0 \pi r^2 (0.00450 \text{ V/m}\cdot\text{s}) .$$

With  $r = 0.0200 \text{ m}$ , this gives  $B = 5.01 \times 10^{-22} \text{ T}$ .

(b) With  $r > R$ , the expression above must be replaced by

$$B(2\pi r) = \epsilon_0 \mu_0 \pi R^2 (0.00450 \text{ V/m}\cdot\text{s}) .$$

Substituting  $r = 0.050 \text{ m}$  and  $R = 0.030 \text{ m}$ , we obtain  $B = 4.51 \times 10^{-22} \text{ T}$ .

11. (a) Here, the enclosed electric flux is found by integrating

$$\Phi_E = \int_0^r E 2\pi r \, dr = t(0.500 \text{ V/m}\cdot\text{s})(2\pi) \int_0^r \left(1 - \frac{r}{R}\right) r \, dr = t\pi \left(\frac{1}{2}r^2 - \frac{r^3}{3R}\right)$$

with SI units understood. Then (after taking the derivative with respect to time) Eq. 32-3 leads to

$$B(2\pi r) = \epsilon_0 \mu_0 \pi \left(\frac{1}{2}r^2 - \frac{r^3}{3R}\right).$$

With  $r = 0.0200 \text{ m}$  and  $R = 0.0300 \text{ m}$ , this gives  $B = 3.09 \times 10^{-20} \text{ T}$ .

(b) The integral shown above will no longer (since now  $r > R$ ) have  $r$  as the upper limit; the upper limit is now  $R$ . Thus,  $\Phi_E = t\pi \left(\frac{1}{2}R^2 - \frac{R^3}{3R}\right) = \frac{1}{6}t\pi R^2$ . Consequently, Eq. 32-3 becomes

$$B(2\pi r) = \frac{1}{6}\epsilon_0 \mu_0 \pi R^2$$

which yields (for  $r = 0.0500 \text{ m}$ )  $B = 1.67 \times 10^{-20} \text{ T}$ .

12. Let the area plate be  $A$  and the plate separation be  $d$ . We use Eq. 32-10:

$$i_d = \epsilon_0 \frac{d\Phi_E}{dt} = \epsilon_0 \frac{d}{dt}(AE) = \epsilon_0 A \frac{d}{dt}\left(\frac{V}{d}\right) = \frac{\epsilon_0 A}{d} \left(\frac{dV}{dt}\right),$$

or

$$\frac{dV}{dt} = \frac{i_d d}{\epsilon_0 A} = \frac{i_d}{C} = \frac{1.5 \text{ A}}{2.0 \times 10^{-6} \text{ F}} = 7.5 \times 10^5 \text{ V/s}.$$

Therefore, we need to change the voltage difference across the capacitor at the rate of  $7.5 \times 10^5 \text{ V/s}$ .

13. The displacement current is given by  $i_d = \epsilon_0 A (dE / dt)$ , where  $A$  is the area of a plate and  $E$  is the magnitude of the electric field between the plates. The field between the plates is uniform, so  $E = V/d$ , where  $V$  is the potential difference across the plates and  $d$  is the plate separation. Thus

$$i_d = \frac{\epsilon_0 A}{d} \frac{dV}{dt}.$$

Now,  $\epsilon_0 A/d$  is the capacitance  $C$  of a parallel-plate capacitor (not filled with a dielectric), so

$$i_d = C \frac{dV}{dt}.$$

14. We use Eq. 32-14:  $i_d = \epsilon_0 A (dE / dt)$ . Note that, in this situation,  $A$  is the area over which a changing electric field is present. In this case  $r > R$ , so  $A = \pi R^2$ . Thus,

$$\frac{dE}{dt} = \frac{i_d}{\epsilon_0 A} = \frac{i_d}{\epsilon_0 \pi R^2} = \frac{2.0 \text{ A}}{\pi \left( 8.85 \times 10^{-12} \frac{\text{C}^2}{\text{N} \cdot \text{m}^2} \right) (0.10 \text{ m})^2} = 7.2 \times 10^{12} \frac{\text{V}}{\text{m} \cdot \text{s}}.$$

15. Consider an area  $A$ , normal to a uniform electric field  $\vec{E}$ . The displacement current density is uniform and normal to the area. Its magnitude is given by  $J_d = i_d/A$ . For this situation,  $i_d = \epsilon_0 A(dE/dt)$ , so

$$J_d = \frac{1}{A} \epsilon_0 A \frac{dE}{dt} = \epsilon_0 \frac{dE}{dt}.$$



16. (a) From Eq. 32-10,

$$\begin{aligned} i_d &= \epsilon_0 \frac{d\Phi_E}{dt} = \epsilon_0 A \frac{dE}{dt} = \epsilon_0 A \frac{d}{dt} \left[ (4.0 \times 10^5) - (6.0 \times 10^4 t) \right] = -\epsilon_0 A (6.0 \times 10^4 \text{ V/m} \cdot \text{s}) \\ &= - \left( 8.85 \times 10^{-12} \frac{\text{C}^2}{\text{N} \cdot \text{m}^2} \right) (4.0 \times 10^{-2} \text{ m}^2) (6.0 \times 10^4 \text{ V/m} \cdot \text{s}) \\ &= -2.1 \times 10^{-8} \text{ A}. \end{aligned}$$

Thus, the magnitude of the displacement current is  $|i_d| = 2.1 \times 10^{-8} \text{ A}$ .

(b) The negative sign in  $i_d$  implies that the direction is downward.

(c) If one draws a counterclockwise circular loop  $s$  around the plates, then according to Eq. 32-18

$$\oint_s \vec{B} \cdot d\vec{s} = \mu_0 i_d < 0,$$

which means that  $\vec{B} \cdot d\vec{s} < 0$ . Thus  $\vec{B}$  must be clockwise.

17. (a) We use  $\oint \vec{B} \cdot d\vec{s} = \mu_0 I_{\text{enclosed}}$  to find

$$B = \frac{\mu_0 I_{\text{enclosed}}}{2\pi r} = \frac{\mu_0 (J_d \pi r^2)}{2\pi r} = \frac{1}{2} \mu_0 J_d r = \frac{1}{2} (1.26 \times 10^{-6} \text{ H/m}) (20 \text{ A/m}^2) (50 \times 10^{-3} \text{ m}) \\ = 6.3 \times 10^{-7} \text{ T}.$$

(b) From  $i_d = J_d \pi r^2 = \epsilon_0 \frac{d\Phi_E}{dt} = \epsilon_0 \pi r^2 \frac{dE}{dt}$ , we get

$$\frac{dE}{dt} = \frac{J_d}{\epsilon_0} = \frac{20 \text{ A/m}^2}{8.85 \times 10^{-12} \text{ F/m}} = 2.3 \times 10^{12} \frac{\text{V}}{\text{m} \cdot \text{s}}.$$

18. (a) Since  $i = i_d$  (Eq. 32-15) then the portion of displacement current enclosed is

$$i_{d,\text{enc}} = i \frac{\pi \left(\frac{R}{3}\right)^2}{\pi R^2} = i \frac{1}{9} = 1.33 \text{ A}.$$

(b) We see from Sample Problems 32-1 and 32-2 that the maximum field is at  $r = R$  and that (in the interior) the field is simply proportional to  $r$ . Therefore,

$$\frac{B}{B_{\text{max}}} = \frac{3.00 \text{ mT}}{12.0 \text{ mT}} = \frac{r}{R}$$

which yields  $r = R/4 = (1.20 \text{ cm})/4 = 0.300 \text{ cm}$ .

(c) We now look for a solution in the exterior region, where the field is inversely proportional to  $r$  (by Eq. 32-17):

$$\frac{B}{B_{\text{max}}} = \frac{3.00 \text{ mT}}{12.0 \text{ mT}} = \frac{R}{r}$$

which yields  $r = 4R = 4(1.20 \text{ cm}) = 4.80 \text{ cm}$ .

19. (a) In region  $a$  of the graph,

$$\begin{aligned} |i_d| &= \varepsilon_0 \left| \frac{d\Phi_E}{dt} \right| = \varepsilon_0 A \left| \frac{dE}{dt} \right| \\ &= (8.85 \times 10^{-12} \text{ F/m})(1.6 \text{ m}^2) \left| \frac{4.5 \times 10^5 \text{ N/C} - 6.0 \times 10^5 \text{ N/C}}{4.0 \times 10^{-6} \text{ s}} \right| = 0.71 \text{ A}. \end{aligned}$$

(b)  $i_d \propto dE/dt = 0$ .

(c) In region  $c$  of the graph,

$$|i_d| = \varepsilon_0 A \left| \frac{dE}{dt} \right| = (8.85 \times 10^{-12} \text{ F/m})(1.6 \text{ m}^2) \left| \frac{-4.0 \times 10^5 \text{ N/C}}{2.0 \times 10^{-6} \text{ s}} \right| = 2.8 \text{ A}.$$

20. From Eq. 28-11, we have  $i = (\mathcal{E} / R) e^{-t/\tau}$  since we are ignoring the self-inductance of the capacitor. Eq. 32-16 gives

$$B = \frac{\mu_0 i_d r}{2\pi R^2} .$$

Furthermore, Eq. 25-9 yields the capacitance

$$C = \frac{\epsilon_0 \pi (0.05 \text{ m})^2}{0.003 \text{ m}} = 2.318 \times 10^{-11} \text{ F},$$

so that the capacitive time constant is  $\tau = (20.0 \times 10^6 \Omega)(2.318 \times 10^{-11} \text{ F}) = 4.636 \times 10^{-4} \text{ s}$ .

At  $t = 250 \times 10^{-6} \text{ s}$ , the current is

$$i = \frac{12.0 \text{ V}}{20.0 \times 10^6 \Omega} e^{-t/\tau} = 3.50 \times 10^{-7} \text{ A} .$$

Since  $i = i_d$  (see Eq. 32-15) and  $r = 0.0300 \text{ m}$ , then (with plate radius  $R = 0.0500 \text{ m}$ ) we find

$$B = \frac{\mu_0 i_d r}{2\pi R^2} = \frac{\mu_0 (3.50 \times 10^{-7})(0.03)}{2\pi (0.05)^2} = 8.40 \times 10^{-13} \text{ T} .$$

21. (a) At any instant the displacement current  $i_d$  in the gap between the plates equals the conduction current  $i$  in the wires. Thus  $i_d = i = 2.0 \text{ A}$ .

(b) The rate of change of the electric field is

$$\frac{dE}{dt} = \frac{1}{\epsilon_0 A} \left( \epsilon_0 \frac{d\Phi_E}{dt} \right) = \frac{i_d}{\epsilon_0 A} = \frac{2.0 \text{ A}}{(8.85 \times 10^{-12} \text{ F/m})(1.0 \text{ m})^2} = 2.3 \times 10^{11} \frac{\text{V}}{\text{m} \cdot \text{s}}.$$

(c) The displacement current through the indicated path is

$$i'_d = i_d \times \left( \frac{d^2}{L^2} \right) = (2.0 \text{ A}) \left( \frac{0.50 \text{ m}}{1.0 \text{ m}} \right)^2 = 0.50 \text{ A}.$$

(d) The integral of the field around the indicated path is

$$\oint \vec{B} \cdot d\vec{s} = \mu_0 i'_d = (1.26 \times 10^{-6} \text{ H/m})(0.50 \text{ A}) = 6.3 \times 10^{-7} \text{ T} \cdot \text{m}.$$

22. (a) Fig. 32-34 indicates that  $i = 4.0$  A when  $t = 20$  ms. Thus,  $B_i = \mu_0 i / 2\pi r = 0.89$  mT.

(b) Fig. 32-34 indicates that  $i = 8.0$  A when  $t = 40$  ms. Thus,  $B_i \approx 0.18$  mT.

(c) Fig. 32-34 indicates that  $i = 10$  A when  $t > 50$  ms. Thus,  $B_i \approx 0.220$  mT.

(d) Eq. 32-4 gives the displacement current in terms of the time-derivative of the electric field:  $i_d = \epsilon_0 A (dE/dt)$ , but using Eq. 26-5 and Eq. 26-10 we have  $E = \rho i / A$  (in terms of the real current); therefore,  $i_d = \epsilon_0 \rho (di/dt)$ . For  $0 < t < 50$  ms, Fig. 32-34 indicates that  $di/dt = 200$  A/s. Thus,  $B_{id} = \mu_0 i_d / 2\pi r = 6.4 \times 10^{-22}$  T.

(e) As in (d),  $B_{id} = \mu_0 i_d / 2\pi r = 6.4 \times 10^{-22}$  T.

(f) Here  $di/dt = 0$ , so (by the reasoning in the previous step)  $B = 0$ .

(g) By the right-hand rule, the direction of  $\vec{B}_i$  at  $t = 20$  s is out of page.

(h) By the right-hand rule, the direction of  $\vec{B}_{id}$  at  $t = 20$  s is out of page.

23. (a) Eq. 32-16 (with Eq. 26-5) gives

$$B = \frac{\mu_0 i_d r}{2\pi R^2} = \frac{\mu_0 J_d A r}{2\pi R^2} = 75.4 \text{ nT}$$

where we set  $A = \pi R^2$  (which led to several cancellations).

(b) Similarly, Eq. 32-17 gives  $B = \frac{\mu_0 i_d}{2\pi r} = \frac{\mu_0 J_d \pi R^2}{2\pi r} = 67.9 \text{ nT}$ .



24. (a) Eq. 32-16 gives  $B = \frac{\mu_0 i_d r}{2\pi R^2} = 2.22 \mu\text{T}$ .

(b) Eq. 32-17 gives  $B = \frac{\mu_0 i_d}{2\pi r} = 2.00 \mu\text{T}$ .

25. (a) Eq. 32-11 applies (though the last term is zero) but we must be careful with  $i_{d,\text{enc}}$ . It is the enclosed portion of the displacement current, and if we related this to the displacement current density  $J_d$ , then

$$i_{d,\text{enc}} = \int_0^r J_d 2\pi r \, dr = (4.00 \text{ A/m}\cdot\text{s})(2\pi) \int_0^r \left(1 - \frac{r}{R}\right) r \, dr = 8\pi \left(\frac{1}{2}r^2 - \frac{r^3}{3R}\right)$$

with SI units understood. Now, we apply Eq. 32-17 (with  $i_d$  replaced with  $i_{d,\text{enc}}$ ) or start from scratch with Eq. 32-11, to get  $B = \frac{\mu_0 i_{d,\text{enc}}}{2\pi r} = 27.9 \text{ nT}$ .

(b) The integral shown above will no longer (since now  $r > R$ ) have  $r$  as the upper limit; the upper limit is now  $R$ . Thus,

$$i_{d,\text{enc}} = i_d = 8\pi \left(\frac{1}{2}R^2 - \frac{R^3}{3R}\right) = \frac{4}{3}\pi R^2.$$

Now Eq. 32-17 gives  $B = \frac{\mu_0 i_d}{2\pi r} = 15.1 \text{ nT}$ .

26. (a) Eq. 32-11 applies (though the last term is zero) but we must be careful with  $i_{d,\text{enc}}$ . It is the enclosed portion of the displacement current. Thus Eq. 32-17 (which derives from Eq. 32-11) becomes, with  $i_d$  replaced with  $i_{d,\text{enc}}$ ,

$$B = \frac{\mu_0 i_{d,\text{enc}}}{2\pi r} = \frac{\mu_0 (3.00 \text{ A}) r}{2\pi r R}$$

which yields (after canceling  $r$ , and setting  $R = 0.0300 \text{ m}$ )  $B = 20.0 \mu \text{ T}$ .

(b) Here  $i_d = 3.00 \text{ A}$ , and we get  $B = \frac{\mu_0 i_d}{2\pi r} = 12.0 \mu \text{ T}$ .

27. The horizontal component of the Earth's magnetic field is given by  $B_h = B \cos \phi_i$ , where  $B$  is the magnitude of the field and  $\phi_i$  is the inclination angle. Thus

$$B = \frac{B_h}{\cos \phi_i} = \frac{16 \mu\text{T}}{\cos 73^\circ} = 55 \mu\text{T} .$$

28. (a) The flux through Arizona is

$$\Phi = -B_r A = -(43 \times 10^{-6} \text{ T})(295,000 \text{ km}^2)(10^3 \text{ m/km})^2 = -1.3 \times 10^7 \text{ Wb} ,$$

inward. By Gauss' law this is equal to the negative value of the flux  $\Phi'$  through the rest of the surface of the Earth. So  $\Phi' = 1.3 \times 10^7 \text{ Wb}$ .

(b) The direction is outward.

29. We use Eq. 32-31:  $\mu_{\text{orb}, z} = -m_\ell \mu_B$ .

(a) For  $m_\ell = 1$ ,  $\mu_{\text{orb}, z} = -(1) (9.3 \times 10^{-24} \text{ J/T}) = -9.3 \times 10^{-24} \text{ J/T}$ .

(b) For  $m_\ell = -2$ ,  $\mu_{\text{orb}, z} = -(-2) (9.3 \times 10^{-24} \text{ J/T}) = 1.9 \times 10^{-23} \text{ J/T}$ .

30. We use Eq. 32-27 to obtain  $\Delta U = -\Delta(\mu_{s,z}B) = -B\Delta\mu_{s,z}$ , where  $\mu_{s,z} = \pm e\hbar/4\pi m_e = \pm\mu_B$  (see Eqs. 32-24 and 32-25). Thus,

$$\Delta U = -B[\mu_B - (-\mu_B)] = 2\mu_B B = 2(9.27 \times 10^{-24} \text{ J/T})(0.25 \text{ T}) = 4.6 \times 10^{-24} \text{ J} .$$

31. (a) Since  $m_\ell = 0$ ,  $L_{\text{orb},z} = m_\ell h/2\pi = 0$ .

(b) Since  $m_\ell = 0$ ,  $\mu_{\text{orb},z} = -m_\ell \mu_B = 0$ .

(c) Since  $m_\ell = 0$ , then from Eq. 32-32,  $U = -\mu_{\text{orb},z} B_{\text{ext}} = -m_\ell \mu_B B_{\text{ext}} = 0$ .

(d) Regardless of the value of  $m_\ell$ , we find for the spin part

$$U = -\mu_{s,z} B = \pm \mu_B B = \pm (9.27 \times 10^{-24} \text{ J/T}) (35 \text{ mT}) = \pm 3.2 \times 10^{-25} \text{ J} .$$

(e) Now  $m_\ell = -3$ , so

$$L_{\text{orb},z} = \frac{m_\ell h}{2\pi} = \frac{(-3) (6.63 \times 10^{-27} \text{ J}\cdot\text{s})}{2\pi} = -3.16 \times 10^{-34} \text{ J}\cdot\text{s} \approx -3.2 \times 10^{-34} \text{ J}\cdot\text{s}$$

(f) and

$$\mu_{\text{orb},z} = -m_\ell \mu_B = -(-3) (9.27 \times 10^{-24} \text{ J/T}) = 2.78 \times 10^{-23} \text{ J/T} \approx 2.8 \times 10^{-23} \text{ J/T} .$$

(g) The potential energy associated with the electron's orbital magnetic moment is now

$$U = -\mu_{\text{orb},z} B_{\text{ext}} = -(2.78 \times 10^{-23} \text{ J/T}) (35 \times 10^{-3} \text{ T}) = -9.7 \times 10^{-25} \text{ J} .$$

(h) On the other hand, the potential energy associated with the electron spin, being independent of  $m_\ell$ , remains the same:  $\pm 3.2 \times 10^{-25} \text{ J}$ .



32. Combining Eq. 32-27 with Eqs. 32-22 and 32-23, we see that the energy difference is

$$\Delta U = 2 \mu_B B$$

where  $\mu_B$  is the Bohr magneton (given in Eq. 32-25). With  $\Delta U = 6.00 \times 10^{-25}$  J, we obtain  $B = 32.3$  mT.

33. (a) The potential energy of the atom in association with the presence of an external magnetic field  $\vec{B}_{\text{ext}}$  is given by Eqs. 32-31 and 32-32:

$$U = -\mu_{\text{orb}} \cdot \vec{B}_{\text{ext}} = -\mu_{\text{orb},z} B_{\text{ext}} = -m_{\ell} \mu_B B_{\text{ext}}.$$

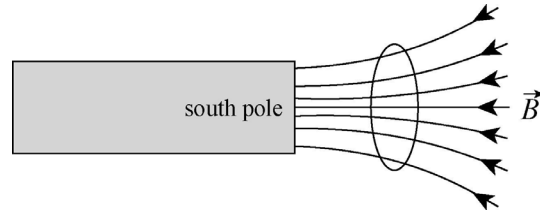
For level  $E_1$  there is no change in energy as a result of the introduction of  $\vec{B}_{\text{ext}}$ , so  $U \propto m_{\ell} = 0$ , meaning that  $m_{\ell} = 0$  for this level.

(b) For level  $E_2$  the single level splits into a triplet (i.e., three separate ones) in the presence of  $\vec{B}_{\text{ext}}$ , meaning that there are three different values of  $m_{\ell}$ . The middle one in the triplet is unshifted from the original value of  $E_2$  so its  $m_{\ell}$  must be equal to 0. The other two in the triplet then correspond to  $m_{\ell} = -1$  and  $m_{\ell} = +1$ , respectively.

(c) For any pair of adjacent levels in the triplet  $|\Delta m_{\ell}| = 1$ . Thus, the spacing is given by

$$\Delta U = |\Delta(-m_{\ell} \mu_B B)| = |\Delta m_{\ell}| \mu_B B = \mu_B B = (9.27 \times 10^{-24} \text{ J/T})(0.50 \text{ T}) = 4.64 \times 10^{-24} \text{ J}.$$

34. (a) A sketch of the field lines (due to the presence of the bar magnet) in the vicinity of the loop is shown below:



(b) The primary conclusion of §32-9 is two-fold:  $\vec{u}$  is opposite to  $\vec{B}$ , and the effect of  $\vec{F}$  is to move the material towards regions of smaller  $|\vec{B}|$  values. The direction of the magnetic moment vector (of our loop) is toward the right in our sketch, or in the  $+x$  direction.

(c) The direction of the current is clockwise (from the perspective of the bar magnet.)

(d) Since the size of  $|\vec{B}|$  relates to the “crowdedness” of the field lines, we see that  $\vec{F}$  is towards the right in our sketch, or in the  $+x$  direction.

35. An electric field with circular field lines is induced as the magnetic field is turned on. Suppose the magnetic field increases linearly from zero to  $B$  in time  $t$ . According to Eq. 31-27, the magnitude of the electric field at the orbit is given by

$$E = \left(\frac{r}{2}\right) \frac{dB}{dt} = \left(\frac{r}{2}\right) \frac{B}{t} ,$$

where  $r$  is the radius of the orbit. The induced electric field is tangent to the orbit and changes the speed of the electron, the change in speed being given by

$$\Delta v = at = \frac{eE}{m_e} t = \left(\frac{e}{m_e}\right) \left(\frac{r}{2}\right) \left(\frac{B}{t}\right) t = \frac{erB}{2m_e} .$$

The average current associated with the circulating electron is  $i = ev/2\pi r$  and the dipole moment is

$$\mu = Ai = (\pi r^2) \left(\frac{ev}{2\pi r}\right) = \frac{1}{2} evr .$$

The change in the dipole moment is

$$\Delta\mu = \frac{1}{2} er\Delta v = \frac{1}{2} er \left(\frac{erB}{2m_e}\right) = \frac{e^2 r^2 B}{4m_e} .$$

36. Reviewing Sample Problem 32-3 before doing this exercise is helpful. Let

$$K = \frac{3}{2} kT = \left| \vec{\mu} \cdot \vec{B} - (-\vec{\mu} \cdot \vec{B}) \right| = 2\mu B$$

which leads to

$$T = \frac{4\mu B}{3k} = \frac{4(1.0 \times 10^{-23} \text{ J/T})(0.50 \text{ T})}{3(1.38 \times 10^{-23} \text{ J/K})} = 0.48 \text{ K} .$$

37. The magnetization is the dipole moment per unit volume, so the dipole moment is given by  $\mu = M V$ , where  $M$  is the magnetization and  $V$  is the volume of the cylinder ( $V = \pi r^2 L$ , where  $r$  is the radius of the cylinder and  $L$  is its length). Thus,

$$\mu = M \pi r^2 L = (5.30 \times 10^3 \text{ A/m}) \pi (0.500 \times 10^{-2} \text{ m})^2 (5.00 \times 10^{-2} \text{ m}) = 2.08 \times 10^{-2} \text{ J/T} .$$

38. (a) From Fig. 32-14 we estimate a slope of  $B/T = 0.50 \text{ T/K}$  when  $M/M_{\text{max}} = 50\%$ . So

$$B = 0.50 \text{ T} = (0.50 \text{ T/K})(300 \text{ K}) = 1.5 \times 10^2 \text{ T}.$$

(b) Similarly, now  $B/T \approx 2$  so  $B = (2)(300) = 6.0 \times 10^2 \text{ T}$ .

(c) Except for very short times and in very small volumes, these values are not attainable in the lab.

39. For the measurements carried out, the largest ratio of the magnetic field to the temperature is  $(0.50 \text{ T})/(10 \text{ K}) = 0.050 \text{ T/K}$ . Look at Fig. 32-14 to see if this is in the region where the magnetization is a linear function of the ratio. It is quite close to the origin, so we conclude that the magnetization obeys Curie's law.



40. Section 32-10 explains the terms used in this problem and the connection between  $M$  and  $\mu$ . The graph in Fig. 32-37 gives a slope of

$$\frac{M/M_{\max}}{B_{\text{ext}}/T} = \frac{0.15}{0.20} = 3/4$$

in Kelvins per Tesla. Thus we can write

$$\frac{\mu}{\mu_{\max}} = \frac{3}{4} (0.800 \text{ T})/(2.00 \text{ K}) = 0.30 .$$

41. (a) A charge  $e$  traveling with uniform speed  $v$  around a circular path of radius  $r$  takes time  $T = 2\pi r/v$  to complete one orbit, so the average current is

$$i = \frac{e}{T} = \frac{ev}{2\pi r}.$$

The magnitude of the dipole moment is this multiplied by the area of the orbit:

$$\mu = \frac{ev}{2\pi r} \pi r^2 = \frac{evr}{2}.$$

Since the magnetic force with magnitude  $evB$  is centripetal, Newton's law yields  $evB = m_e v^2/r$ , so  $r = m_e v / eB$ . Thus,

$$\mu = \frac{1}{2}(ev)\left(\frac{m_e v}{eB}\right) = \left(\frac{1}{B}\right)\left(\frac{1}{2}m_e v^2\right) = \frac{K_e}{B}.$$

The magnetic force  $-e\vec{v} \times \vec{B}$  must point toward the center of the circular path. If the magnetic field is directed out of the page (defined to be  $+z$  direction), the electron will travel counterclockwise around the circle. Since the electron is negative, the current is in the opposite direction, clockwise and, by the right-hand rule for dipole moments, the dipole moment is into the page, or in the  $-z$  direction. That is, the dipole moment is directed opposite to the magnetic field vector.

(b) We note that the charge canceled in the derivation of  $\mu = K_e/B$ . Thus, the relation  $\mu = K_i/B$  holds for a positive ion.

(c) The direction of the dipole moment is  $-z$ , opposite to the magnetic field.

(d) The magnetization is given by  $M = \mu_e n_e + \mu_i n_i$ , where  $\mu_e$  is the dipole moment of an electron,  $n_e$  is the electron concentration,  $\mu_i$  is the dipole moment of an ion, and  $n_i$  is the ion concentration. Since  $n_e = n_i$ , we may write  $n$  for both concentrations. We substitute  $\mu_e = K_e/B$  and  $\mu_i = K_i/B$  to obtain

$$M = \frac{n}{B}(K_e + K_i) = \frac{5.3 \times 10^{21} \text{ m}^{-3}}{1.2 \text{ T}} (6.2 \times 10^{-20} \text{ J} + 7.6 \times 10^{-21} \text{ J}) = 3.1 \times 10^2 \text{ A/m}.$$

42. The Curie temperature for iron is  $770^{\circ}\text{C}$ . If  $x$  is the depth at which the temperature has this value, then  $10^{\circ}\text{C} + (30^{\circ}\text{C}/\text{km})x = 770^{\circ}\text{C}$ . Therefore,

$$x = \frac{770^{\circ}\text{C} - 10^{\circ}\text{C}}{30^{\circ}\text{C}/\text{km}} = 25\text{ km}.$$

43. (a) The field of a dipole along its axis is given by Eq. 30-29:

$$B = \frac{\mu_0}{2\pi} \frac{\mu}{z^3},$$

where  $\mu$  is the dipole moment and  $z$  is the distance from the dipole. Thus,

$$B = \frac{(4\pi \times 10^{-7} \text{ T} \cdot \text{m/A})(1.5 \times 10^{-23} \text{ J/T})}{2\pi(10 \times 10^{-9} \text{ m})} = 3.0 \times 10^{-6} \text{ T}.$$

(b) The energy of a magnetic dipole  $\vec{\mu}$  in a magnetic field  $\vec{B}$  is given by  $U = -\vec{\mu} \cdot \vec{B} = -\mu B \cos \phi$ , where  $\phi$  is the angle between the dipole moment and the field. The energy required to turn it end-for-end (from  $\phi = 0^\circ$  to  $\phi = 180^\circ$ ) is

$$\Delta U = 2\mu B = 2(1.5 \times 10^{-23} \text{ J/T})(3.0 \times 10^{-6} \text{ T}) = 9.0 \times 10^{-29} \text{ J} = 5.6 \times 10^{-10} \text{ eV}.$$

The mean kinetic energy of translation at room temperature is about 0.04 eV. Thus, if dipole-dipole interactions were responsible for aligning dipoles, collisions would easily randomize the directions of the moments and they would not remain aligned.

44. (a) The number of iron atoms in the iron bar is

$$N = \frac{(7.9 \text{ g/cm}^3)(5.0 \text{ cm})(1.0 \text{ cm}^2)}{(55.847 \text{ g/mol}) / (6.022 \times 10^{23} / \text{mol})} = 4.3 \times 10^{23}.$$

Thus the dipole moment of the iron bar is

$$\mu = (2.1 \times 10^{-23} \text{ J/T})(4.3 \times 10^{23}) = 8.9 \text{ A} \cdot \text{m}^2.$$

$$(b) \tau = \mu B \sin 90^\circ = (8.9 \text{ A} \cdot \text{m}^2)(1.57 \text{ T}) = 13 \text{ N} \cdot \text{m}.$$

45. The saturation magnetization corresponds to complete alignment of all atomic dipoles and is given by  $M_{\text{sat}} = \mu n$ , where  $n$  is the number of atoms per unit volume and  $\mu$  is the magnetic dipole moment of an atom. The number of nickel atoms per unit volume is  $n = \rho/m$ , where  $\rho$  is the density of nickel. The mass of a single nickel atom is calculated using  $m = M/N_A$ , where  $M$  is the atomic mass of nickel and  $N_A$  is Avogadro's constant. Thus,

$$n = \frac{\rho N_A}{M} = \frac{(8.90 \text{ g/cm}^3)(6.02 \times 10^{23} \text{ atoms/mol})}{58.71 \text{ g/mol}} = 9.126 \times 10^{22} \text{ atoms/cm}^3$$

$$= 9.126 \times 10^{28} \text{ atoms/m}^3.$$

The dipole moment of a single atom of nickel is

$$\mu = \frac{M_{\text{sat}}}{n} = \frac{4.70 \times 10^5 \text{ A/m}}{9.126 \times 10^{28} \text{ m}^{-3}} = 5.15 \times 10^{-24} \text{ A} \cdot \text{m}^2.$$

46. (a) Eq. 29-36 gives

$$\tau = \mu_{\text{rod}} B \sin \theta = (2700 \text{ A/m})(0.06 \text{ m})\pi(0.003 \text{ m})^2(0.035 \text{ T})\sin(68^\circ) = 1.49 \times 10^{-4} \text{ N}\cdot\text{m}.$$

We have used the fact that the volume of a cylinder is its length times its (circular) cross sectional area.

(b) Using Eq. 29-38, we have

$$\begin{aligned}\Delta U &= -\mu_{\text{rod}} B (\cos \theta_f - \cos \theta_i) \\ &= -(2700 \text{ A/m})(0.06 \text{ m})\pi(0.003 \text{ m})^2(0.035 \text{ T})[\cos(34^\circ) - \cos(68^\circ)] \\ &= -72.9 \text{ }\mu\text{J}.\end{aligned}$$

47. (a) The magnitude of the toroidal field is given by  $B_0 = \mu_0 n i_p$ , where  $n$  is the number of turns per unit length of toroid and  $i_p$  is the current required to produce the field (in the absence of the ferromagnetic material). We use the average radius ( $r_{\text{avg}} = 5.5 \text{ cm}$ ) to calculate  $n$ :

$$n = \frac{N}{2\pi r_{\text{avg}}} = \frac{400 \text{ turns}}{2\pi(5.5 \times 10^{-2} \text{ m})} = 1.16 \times 10^3 \text{ turns/m} .$$

Thus,

$$i_p = \frac{B_0}{\mu_0 n} = \frac{0.20 \times 10^{-3} \text{ T}}{(4\pi \times 10^{-7} \text{ T} \cdot \text{m} / \text{A})(1.16 \times 10^3 / \text{m})} = 0.14 \text{ A} .$$

(b) If  $\Phi$  is the magnetic flux through the secondary coil, then the magnitude of the emf induced in that coil is  $\mathcal{E} = N(d\Phi/dt)$  and the current in the secondary is  $i_s = \mathcal{E}/R$ , where  $R$  is the resistance of the coil. Thus,

$$i_s = \left( \frac{N}{R} \right) \frac{d\Phi}{dt} .$$

The charge that passes through the secondary when the primary current is turned on is

$$q = \int i_s dt = \frac{N}{R} \int \frac{d\Phi}{dt} dt = \frac{N}{R} \int_0^\Phi d\Phi = \frac{N\Phi}{R} .$$

The magnetic field through the secondary coil has magnitude  $B = B_0 + B_M = 801B_0$ , where  $B_M$  is the field of the magnetic dipoles in the magnetic material. The total field is perpendicular to the plane of the secondary coil, so the magnetic flux is  $\Phi = AB$ , where  $A$  is the area of the Rowland ring (the field is inside the ring, not in the region between the ring and coil). If  $r$  is the radius of the ring's cross section, then  $A = \pi r^2$ . Thus,

$$\Phi = 801\pi r^2 B_0 .$$

The radius  $r$  is  $(6.0 \text{ cm} - 5.0 \text{ cm})/2 = 0.50 \text{ cm}$  and

$$\Phi = 801\pi(0.50 \times 10^{-2} \text{ m})^2 (0.20 \times 10^{-3} \text{ T}) = 1.26 \times 10^{-5} \text{ Wb} .$$

Consequently,

$$q = \frac{50(1.26 \times 10^{-5} \text{ Wb})}{8.0 \Omega} = 7.9 \times 10^{-5} \text{ C} .$$



48. From Eq. 29-37 (see also Eq. 29-36) we write the torque as  $\tau = -\mu B_h \sin\theta$  where the minus indicates that the torque opposes the angular displacement  $\theta$  (which we will assume is small and in radians). The small angle approximation leads to  $\tau \approx -\mu B_h \theta$ , which is an indicator for simple harmonic motion (see section 16-5, especially Eq. 16-22). Comparing with Eq. 16-23, we then find the period of oscillation is

$$T = 2\pi \sqrt{\frac{I}{\mu B_h}}$$

where  $I$  is the rotational inertial that we asked to solve for. Since the frequency is given as 0.312 Hz, then the period is  $T = 1/f = 1/0.312$  in SI units. Similarly,  $B_h = 18.0 \times 10^{-6}$  and  $\mu = 6.80 \times 10^{-4}$ . The above relation then yields  $I = 3.19 \times 10^{-9} \text{ kg m}^2$ .

49. (a) If the magnetization of the sphere is saturated, the total dipole moment is  $\mu_{\text{total}} = N\mu$ , where  $N$  is the number of iron atoms in the sphere and  $\mu$  is the dipole moment of an iron atom. We wish to find the radius of an iron sphere with  $N$  iron atoms. The mass of such a sphere is  $Nm$ , where  $m$  is the mass of an iron atom. It is also given by  $4\pi\rho R^3/3$ , where  $\rho$  is the density of iron and  $R$  is the radius of the sphere. Thus  $Nm = 4\pi\rho R^3/3$  and

$$N = \frac{4\pi\rho R^3}{3m}.$$

We substitute this into  $\mu_{\text{total}} = N\mu$  to obtain

$$\mu_{\text{total}} = \frac{4\pi\rho R^3 \mu}{3m}.$$

We solve for  $R$  and obtain

$$R = \left( \frac{3m\mu_{\text{total}}}{4\pi\rho\mu} \right)^{1/3}.$$

The mass of an iron atom is  $m = 56 \text{ u} = (56 \text{ u})(1.66 \times 10^{-27} \text{ kg/u}) = 9.30 \times 10^{-26} \text{ kg}$ . Therefore,

$$R = \left[ \frac{3(9.30 \times 10^{-26} \text{ kg})(8.0 \times 10^{22} \text{ J/T})}{4\pi(14 \times 10^3 \text{ kg/m}^3)(2.1 \times 10^{-23} \text{ J/T})} \right]^{1/3} = 1.8 \times 10^5 \text{ m}.$$

(b) The volume of the sphere is  $V_s = \frac{4\pi}{3} R^3 = \frac{4\pi}{3} (1.82 \times 10^5 \text{ m})^3 = 2.53 \times 10^{16} \text{ m}^3$  and the volume of the Earth is

$$V_e = \frac{4\pi}{3} (6.37 \times 10^6 \text{ m})^3 = 1.08 \times 10^{21} \text{ m}^3,$$

so the fraction of the Earth's volume that is occupied by the sphere is

$$\frac{2.53 \times 10^{16} \text{ m}^3}{1.08 \times 10^{21} \text{ m}^3} = 2.3 \times 10^{-5}.$$

50. The integral of the field along the indicated path is, by Eq. 32-18 and Eq. 32-19, equal to

$$\mu_0 i_d (\text{enclosed area}) / (\text{total area}) = \mu_0 (0.75 \text{ A}) (4 \text{ cm} \times 2 \text{ cm}) / (12 \text{ cm})^2 = 52 \text{ nT}\cdot\text{m}.$$

51. (a) Inside the gap of the capacitor,  $B_1 = \mu_0 i_d r_1 / 2\pi R^2$  (Eq. 32-16); outside the gap the magnetic field is  $B_2 = \mu_0 i_d / 2\pi r_2$  (Eq. 32-17). Consequently,  $B_2 = B_1 R^2 / r_1 r_2 = 16.7 \text{ nT}$ .

(b) The displacement current is  $i_d = 2\pi B_1 R^2 / \mu_0 r_1 = 5.00 \text{ mA}$ .

52. (a) The period of rotation is  $T = 2\pi/\omega$  and in this time all the charge passes any fixed point near the ring. The average current is  $i = q/T = q\omega/2\pi$  and the magnitude of the magnetic dipole moment is

$$\mu = iA = \frac{q\omega}{2\pi} \pi r^2 = \frac{1}{2} q \omega r^2 .$$

(b) We curl the fingers of our right hand in the direction of rotation. Since the charge is positive, the thumb points in the direction of the dipole moment. It is the same as the direction of the angular momentum vector of the ring.

53. (a) We use the result of part (a) in Sample Problem 32-1:

$$B = \frac{\mu_0 \epsilon_0 r}{2} \frac{dE}{dt} \quad (\text{for } r \leq R),$$

where  $r = 0.80R$  and

$$\frac{dE}{dt} = \frac{d}{dt} \left( \frac{V}{d} \right) = \frac{1}{d} \frac{d}{dt} (V_0 e^{-t/\tau}) = -\frac{V_0}{\tau d} e^{-t/\tau}.$$

Here  $V_0 = 100 \text{ V}$ . Thus

$$\begin{aligned} B(t) &= \left( \frac{\mu_0 \epsilon_0 r}{2} \right) \left( -\frac{V_0}{\tau d} e^{-t/\tau} \right) = -\frac{\mu_0 \epsilon_0 V_0 r}{2 \tau d} e^{-t/\tau} \\ &= -\frac{(4\pi \times 10^{-7} \text{ T} \cdot \text{m/A}) (8.85 \times 10^{-12} \frac{\text{C}^2}{\text{N} \cdot \text{m}^2}) (100 \text{ V}) (0.80) (16 \text{ mm})}{2 (12 \times 10^{-3} \text{ s}) (5.0 \text{ mm})} e^{-t/12 \text{ ms}} \\ &= -(1.2 \times 10^{-13} \text{ T}) e^{-t/12 \text{ ms}}. \end{aligned}$$

The magnitude is  $|B(t)| = (1.2 \times 10^{-13} \text{ T}) e^{-t/12 \text{ ms}}$ .

(b) At time  $t = 3\tau$ ,  $B(t) = -(1.2 \times 10^{-13} \text{ T}) e^{-3\tau/\tau} = -5.9 \times 10^{-15} \text{ T}$ , with a magnitude  $|B(t)| = 5.9 \times 10^{-15} \text{ T}$ .

54. (a) Eq. 30-22 gives  $B = \frac{\mu_0 i r}{2\pi R^2} = 222 \mu\text{T}$ .

(b) Eq. 30-19 (or Eq. 30-6) gives  $B = \frac{\mu_0 i}{2\pi r} = 167 \mu\text{T}$ .

(c) As in part (b), we obtain a field of  $\frac{\mu_0 i}{2\pi r} = 22.7 \mu\text{T}$ .

(d) Eq. 32-16 (with Eq. 32-15) gives  $B = \frac{\mu_0 i_d r}{2\pi R^2} = 1.25 \mu\text{T}$ .

(e) As in part (d), we get  $\frac{\mu_0 i_d r}{2\pi R^2} = 3.75 \mu\text{T}$ .

(f) Eq. 32-17 yields  $B = 22.7 \mu\text{T}$ .

(g) Because the displacement current in the gap is spread over a larger cross-sectional area, values of  $B$  within that area are relatively small. Outside that cross-sectional area, the two values of  $B$  are identical. See Fig. 32-23*b*.

55. (a) Again from Fig. 32-14, for  $M/M_{\max} = 50\%$  we have  $B/T = 0.50$ . So  $T = B/0.50 = 2/0.50 = 4$  K.

(b) Now  $B/T = 2.0$ , so  $T = 2/2.0 = 1$  K.



56. (a) The complete set of values are  $\{-4, -3, -2, -1, 0, +1, +2, +3, +4\} \Rightarrow$  nine values in all.

(b) The maximum value is  $4\mu_B = 3.71 \times 10^{-23} \text{ J/T}$ .

(c) Multiplying our result for part (b) by 0.250 T gives  $U = +9.27 \times 10^{-24} \text{ J}$ .

(d) Similarly, for the lower limit,  $U = -9.27 \times 10^{-24} \text{ J}$ .

57. (a) Using Eq. 27-10, we find  $E = \rho J = \frac{\rho i}{A} = \frac{(1.62 \times 10^{-8} \Omega \cdot \text{m})(100 \text{ A})}{5.00 \times 10^{-6} \text{ m}^2} = 0.324 \text{ V/m}.$

(b) The displacement current is

$$i_d = \epsilon_0 \frac{d\Phi_E}{dt} = \epsilon_0 A \frac{dE}{dt} = \epsilon_0 A \frac{d}{dt} \left( \frac{\rho i}{A} \right) = \epsilon_0 \rho \frac{di}{dt} = (8.85 \times 10^{-12} \text{ F})(1.62 \times 10^{-8} \Omega)(2000 \text{ A/s})$$

$$= 2.87 \times 10^{-16} \text{ A}.$$

(c) The ratio of fields is  $\frac{B(\text{due to } i_d)}{B(\text{due to } i)} = \frac{\mu_0 i_d / 2\pi r}{\mu_0 i / 2\pi r} = \frac{i_d}{i} = \frac{2.87 \times 10^{-16} \text{ A}}{100 \text{ A}} = 2.87 \times 10^{-18}.$

58. (a) Using Eq. 32-31, we find

$$\mu_{\text{orb},z} = -3\mu_B = -2.78 \times 10^{-23} \text{ J/T}.$$

(That these are acceptable units for magnetic moment is seen from Eq. 32-32 or Eq. 32-27; they are equivalent to  $\text{A}\cdot\text{m}^2$ ).

(b) Similarly, for  $m_\ell = -4$  we obtain  $\mu_{\text{orb},z} = 3.71 \times 10^{-23} \text{ J/T}$ .

59. Let the area of each circular plate be  $A$  and that of the central circular section be  $a$ , then

$$\frac{A}{a} = \frac{\pi R^2}{\pi (R/2)^2} = 4 .$$

Thus, from Eqs. 32-14 and 32-15 the total discharge current is given by  $i = i_d = 4(2.0 \text{ A}) = 8.0 \text{ A}$ .

60. The interacting potential energy between the magnetic dipole of the compass and the Earth's magnetic field is  $U = -\vec{\mu} \cdot \vec{B}_e = -\mu B_e \cos \theta$ , where  $\theta$  is the angle between  $\vec{\mu}$  and  $\vec{B}_e$ . For small angle  $\theta$

$$U(\theta) = -\mu B_e \cos \theta \approx -\mu B_e \left(1 - \frac{\theta^2}{2}\right) = \frac{1}{2} \kappa \theta^2 - \mu B_e$$

where  $\kappa = \mu B_e$ . Conservation of energy for the compass then gives

$$\frac{1}{2} I \left( \frac{d\theta}{dt} \right)^2 + \frac{1}{2} \kappa \theta^2 = \text{const.}$$

This is to be compared with the following expression for the mechanical energy of a spring-mass system:

$$\frac{1}{2} m \left( \frac{dx}{dt} \right)^2 + \frac{1}{2} k x^2 = \text{const.},$$

which yields  $\omega = \sqrt{k/m}$ . So by analogy, in our case

$$\omega = \sqrt{\frac{\kappa}{I}} = \sqrt{\frac{\mu B_e}{I}} = \sqrt{\frac{\mu B_e}{ml^2/12}},$$

which leads to

$$\mu = \frac{ml^2 \omega^2}{12 B_e} = \frac{(0.050 \text{ kg})(4.0 \times 10^{-2} \text{ m})^2 (45 \text{ rad/s})^2}{12(16 \times 10^{-6} \text{ T})} = 8.4 \times 10^2 \text{ J/T}.$$

61. (a) At any instant the displacement current  $i_d$  in the gap between the plates equals the conduction current  $i$  in the wires. Thus  $i_{\max} = i_{d\max} = 7.60 \mu\text{A}$ .

(b) Since  $i_d = \epsilon_0 (d\Phi_E/dt)$ ,

$$\left( \frac{d\Phi_E}{dt} \right)_{\max} = \frac{i_{d\max}}{\epsilon_0} = \frac{7.60 \times 10^{-6} \text{ A}}{8.85 \times 10^{-12} \text{ F/m}} = 8.59 \times 10^5 \text{ V} \cdot \text{m/s}.$$

(c) According to problem 13,

$$i_d = C \frac{dV}{dt} = \frac{\epsilon_0 A}{d} \frac{dV}{dt}.$$

Now the potential difference across the capacitor is the same in magnitude as the emf of the generator, so  $V = \epsilon_m \sin \omega t$  and  $dV/dt = \omega \epsilon_m \cos \omega t$ . Thus,  $i_d = (\epsilon_0 A \omega \epsilon_m / d) \cos \omega t$  and  $i_{d\max} = \epsilon_0 A \omega \epsilon_m / d$ . This means

$$d = \frac{\epsilon_0 A \omega \epsilon_m}{i_{d\max}} = \frac{(8.85 \times 10^{-12} \text{ F/m}) \pi (0.180 \text{ m})^2 (130 \text{ rad/s}) (220 \text{ V})}{7.60 \times 10^{-6} \text{ A}} = 3.39 \times 10^{-3} \text{ m},$$

where  $A = \pi R^2$  was used.

(d) We use the Ampere-Maxwell law in the form  $\oint \vec{B} \cdot d\vec{s} = \mu_0 I_d$ , where the path of integration is a circle of radius  $r$  between the plates and parallel to them.  $I_d$  is the displacement current through the area bounded by the path of integration. Since the displacement current density is uniform between the plates,  $I_d = (r^2/R^2) i_d$ , where  $i_d$  is the total displacement current between the plates and  $R$  is the plate radius. The field lines are circles centered on the axis of the plates, so  $\vec{B}$  is parallel to  $d\vec{s}$ . The field has constant magnitude around the circular path, so  $\oint \vec{B} \cdot d\vec{s} = 2\pi r B$ . Thus,

$$2\pi r B = \mu_0 \left( \frac{r^2}{R^2} \right) i_d \Rightarrow B = \frac{\mu_0 i_d r}{2\pi R^2}.$$

The maximum magnetic field is given by

$$B_{\max} = \frac{\mu_0 i_{d\max} r}{2\pi R^2} = \frac{(4\pi \times 10^{-7} \text{ T} \cdot \text{m/A}) (7.6 \times 10^{-6} \text{ A}) (0.110 \text{ m})}{2\pi (0.180 \text{ m})^2} = 5.16 \times 10^{-12} \text{ T}.$$

62. The definition of displacement current is Eq. 32-10, and the formula of greatest convenience here is Eq. 32-17:

$$i_d = \frac{2\pi r B}{\mu_0} = \frac{2\pi(0.0300\text{ m})(2.00 \times 10^{-6}\text{ T})}{4\pi \times 10^{-7}\text{ T} \cdot \text{m/A}} = 0.300\text{ A} .$$

63. (a) For a given value of  $\ell$ ,  $m_\ell$  varies from  $-\ell$  to  $+\ell$ . Thus, in our case  $\ell = 3$ , and the number of different  $m_\ell$ 's is  $2\ell + 1 = 2(3) + 1 = 7$ . Thus, since  $L_{\text{orb},z} \propto m_\ell$ , there are a total of seven different values of  $L_{\text{orb},z}$ .

(b) Similarly, since  $\mu_{\text{orb},z} \propto m_\ell$ , there are also a total of seven different values of  $\mu_{\text{orb},z}$ .

(c) Since  $L_{\text{orb},z} = m_\ell h/2\pi$ , the greatest allowed value of  $L_{\text{orb},z}$  is given by  $|m_\ell|_{\text{max}} h/2\pi = 3h/2\pi$ .

(d) Similar to part (c), since  $\mu_{\text{orb},z} = -m_\ell \mu_B$ , the greatest allowed value of  $\mu_{\text{orb},z}$  is given by  $|m_\ell|_{\text{max}} \mu_B = 3eh/4\pi m_e$ .

(e) From Eqs. 32-23 and 32-29 the  $z$  component of the net angular momentum of the electron is given by

$$L_{\text{net},z} = L_{\text{orb},z} + L_{s,z} = \frac{m_\ell h}{2\pi} + \frac{m_s h}{2\pi}.$$

For the maximum value of  $L_{\text{net},z}$  let  $m_\ell = [m_\ell]_{\text{max}} = 3$  and  $m_s = \frac{1}{2}$ . Thus

$$[L_{\text{net},z}]_{\text{max}} = \left(3 + \frac{1}{2}\right) \frac{h}{2\pi} = \frac{3.5h}{2\pi}.$$

(f) Since the maximum value of  $L_{\text{net},z}$  is given by  $[m_J]_{\text{max}} h/2\pi$  with  $[m_J]_{\text{max}} = 3.5$  (see the last part above), the number of allowed values for the  $z$  component of  $L_{\text{net},z}$  is given by  $2[m_J]_{\text{max}} + 1 = 2(3.5) + 1 = 8$ .

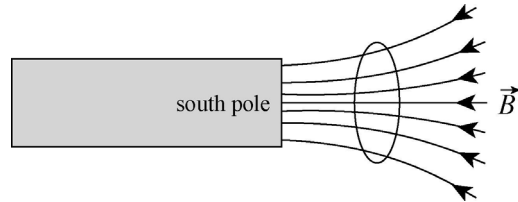


64. Ignoring points where the determination of the slope is problematic, we find the interval of largest  $\Delta|\vec{E}|/\Delta t$  is  $6\ \mu\text{s} < t < 7\ \mu\text{s}$ . During that time, we have, from Eq. 32-14,

$$i_d = \epsilon_0 A \frac{\Delta|\vec{E}|}{\Delta t} = \epsilon_0 (2.0\text{ m}^2) (2.0 \times 10^6\text{ V/m})$$

which yields  $i_d = 3.5 \times 10^{-5}\text{ A}$ .

65. (a) A sketch of the field lines (due to the presence of the bar magnet) in the vicinity of the loop is shown below:



(b) For paramagnetic materials, the dipole moment  $\vec{\mu}$  is in the same direction as  $\vec{B}$ . From the above figure,  $\vec{\mu}$  points in the  $-x$  direction.

(c) From the right-hand rule, since  $\vec{\mu}$  points in the  $-x$  direction, the current flows counterclockwise, from the perspective of the bar magnet.

(d) The effect of  $\vec{F}$  is to move the material towards regions of larger  $|\vec{B}|$  values. Since the size of  $|\vec{B}|$  relates to the “crowdedness” of the field lines, we see that  $\vec{F}$  is towards the left, or  $-x$ .

66. (a) From Eq. 21-3,

$$E = \frac{e}{4\pi\epsilon_0 r^2} = \frac{(1.60 \times 10^{-19} \text{ C})(8.99 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2)}{(5.2 \times 10^{-11} \text{ m})^2} = 5.3 \times 10^{11} \text{ N/C} .$$

(b) We use Eq. 29-28:

$$B = \frac{\mu_0 \mu_p}{2\pi r^3} = \frac{(4\pi \times 10^{-7} \text{ T} \cdot \text{m/A})(1.4 \times 10^{-26} \text{ J/T})}{2\pi(5.2 \times 10^{-11} \text{ m})^3} = 2.0 \times 10^{-2} \text{ T} .$$

(c) From Eq. 32-30,

$$\frac{\mu_{\text{orb}}}{\mu_p} = \frac{eh/4\pi m_e}{\mu_p} = \frac{\mu_B}{\mu_p} = \frac{9.27 \times 10^{-24} \text{ J/T}}{1.4 \times 10^{-26} \text{ J/T}} = 6.6 \times 10^2 .$$

67. (a) From  $\mu = iA = i\pi R_e^2$  we get

$$i = \frac{\mu}{\pi R_e^2} = \frac{8.0 \times 10^{22} \text{ J / T}}{\pi (6.37 \times 10^6 \text{ m})^2} = 6.3 \times 10^8 \text{ A} .$$

(b) Yes, because far away from the Earth the fields of both the Earth itself and the current loop are dipole fields. If these two dipoles cancel each other out, then the net field will be zero.

(c) No, because the field of the current loop is not that of a magnetic dipole in the region close to the loop.

68. (a) Using Eq. 32-13 but noting that the capacitor is being *discharged*, we have

$$\frac{d|\vec{E}|}{dt} = -\frac{i}{\epsilon_0 A} = -8.8 \times 10^{15}$$

where  $A = (0.0080)^2$  and SI units are understood.

(b) Assuming a perfectly uniform field, even so near to an edge (which is consistent with the fact that fringing is neglected in §32-4), we follow part (a) of Sample Problem 32-2 and relate the (absolute value of the) line integral to the portion of displacement current enclosed.

$$\left| \oint \vec{B} \cdot d\vec{s} \right| = \mu_0 i_{d,\text{enc}} = \mu_0 \left( \frac{WH}{L^2} i \right) = 5.9 \times 10^{-7} \text{ Wb/m.}$$

69. (a) We use the notation  $P(\mu)$  for the probability of a dipole being parallel to  $\vec{B}$ , and  $P(-\mu)$  for the probability of a dipole being antiparallel to the field. The magnetization may be thought of as a “weighted average” in terms of these probabilities:

$$M = \frac{N\mu P(\mu) - N\mu P(-\mu)}{P(\mu) + P(-\mu)} = \frac{N\mu(e^{\mu B/kT} - e^{-\mu B/kT})}{e^{\mu B/kT} + e^{-\mu B/kT}} = N\mu \tanh\left(\frac{\mu B}{kT}\right).$$

(b) For  $\mu B \ll kT$  (that is,  $\mu B / kT \ll 1$ ) we have  $e^{\pm\mu B/kT} \approx 1 \pm \mu B/kT$ , so

$$M = N\mu \tanh\left(\frac{\mu B}{kT}\right) \approx \frac{N\mu[(1 + \mu B/kT) - (1 - \mu B/kT)]}{(1 + \mu B/kT) + (1 - \mu B/kT)} = \frac{N\mu^2 B}{kT}.$$

(c) For  $\mu B \gg kT$  we have  $\tanh(\mu B/kT) \approx 1$ , so  $M = N\mu \tanh\left(\frac{\mu B}{kT}\right) \approx N\mu$ .

(d) One can easily plot the tanh function using, for instance, a graphical calculator. One can then note the resemblance between such a plot and Fig. 32-14. By adjusting the parameters used in one’s plot, the curve in Fig. 32-14 can reliably be fit with a tanh function.

70. (a) From Eq. 32-1, we have

$$(\Phi_B)_{\text{in}} = (\Phi_B)_{\text{out}} = 0.0070 \text{ Wb} + (0.40 \text{ T})(\pi r^2) = 9.2 \times 10^{-3} \text{ Wb}.$$

Thus, the magnetic of the magnetic flux is 9.2 mWb.

(b) The flux is inward.

71. (a) The Pythagorean theorem leads to

$$\begin{aligned} B &= \sqrt{B_h^2 + B_v^2} = \sqrt{\left(\frac{\mu_0 \mu}{4\pi r^3} \cos \lambda_m\right)^2 + \left(\frac{\mu_0 \mu}{2\pi r^3} \sin \lambda_m\right)^2} = \frac{\mu_0 \mu}{4\pi r^3} \sqrt{\cos^2 \lambda_m + 4 \sin^2 \lambda_m} \\ &= \frac{\mu_0 \mu}{4\pi r^3} \sqrt{1 + 3 \sin^2 \lambda_m}, \end{aligned}$$

where  $\cos^2 \lambda_m + \sin^2 \lambda_m = 1$  was used.

(b) We use Eq. 3-6:

$$\tan \phi_i = \frac{B_v}{B_h} = \frac{(\mu_0 \mu / 2\pi r^3) \sin \lambda_m}{(\mu_0 \mu / 4\pi r^3) \cos \lambda_m} = 2 \tan \lambda_m .$$



72. (a) At the magnetic equator ( $\lambda_m = 0$ ), the field is

$$B = \frac{\mu_0 \mu}{4\pi r^3} = \frac{(4\pi \times 10^{-7} \text{ T} \cdot \text{m/A}) (8.00 \times 10^{22} \text{ A} \cdot \text{m}^2)}{4\pi (6.37 \times 10^6 \text{ m})^3} = 3.10 \times 10^{-5} \text{ T}.$$

(b)  $\phi_i = \tan^{-1} (2 \tan \lambda_m) = \tan^{-1} (0) = 0^\circ$ .

(c) At  $\lambda_m = 60.0^\circ$ , we find

$$B = \frac{\mu_0 \mu}{4\pi r^3} \sqrt{1 + 3 \sin^2 \lambda_m} = (3.10 \times 10^{-5}) \sqrt{1 + 3 \sin^2 60.0^\circ} = 5.59 \times 10^{-5} \text{ T}.$$

(d)  $\phi_i = \tan^{-1} (2 \tan 60.0^\circ) = 73.9^\circ$ .

(e) At the north magnetic pole ( $\lambda_m = 90.0^\circ$ ), we obtain

$$B = \frac{\mu_0 \mu}{4\pi r^3} \sqrt{1 + 3 \sin^2 \lambda_m} = (3.10 \times 10^{-5}) \sqrt{1 + 3 (1.00)^2} = 6.20 \times 10^{-5} \text{ T}.$$

(f)  $\phi_i = \tan^{-1} (2 \tan 90.0^\circ) = 90.0^\circ$ .

73. (a) At a distance  $r$  from the center of the Earth, the magnitude of the magnetic field is given by

$$B = \frac{\mu_0 \mu}{4\pi r^3} \sqrt{1 + 3 \sin^2 \lambda_m} ,$$

where  $\mu$  is the Earth's dipole moment and  $\lambda_m$  is the magnetic latitude. The ratio of the field magnitudes for two different distances at the same latitude is

$$\frac{B_2}{B_1} = \frac{r_1^3}{r_2^3} .$$

With  $B_1$  being the value at the surface and  $B_2$  being half of  $B_1$ , we set  $r_1$  equal to the radius  $R_e$  of the Earth and  $r_2$  equal to  $R_e + h$ , where  $h$  is altitude at which  $B$  is half its value at the surface. Thus,

$$\frac{1}{2} = \frac{R_e^3}{(R_e + h)^3} .$$

Taking the cube root of both sides and solving for  $h$ , we get

$$h = (2^{1/3} - 1) R_e = (2^{1/3} - 1)(6370 \text{ km}) = 1.66 \times 10^3 \text{ km} .$$

(b) We use the expression for  $B$  obtained in problem 6, part (a). For maximum  $B$ , we set  $\sin \lambda_m = 1.00$ . Also,  $r = 6370 \text{ km} - 2900 \text{ km} = 3470 \text{ km}$ . Thus,

$$\begin{aligned} B_{\max} &= \frac{\mu_0 \mu}{4\pi r^3} \sqrt{1 + 3 \sin^2 \lambda_m} = \frac{(4\pi \times 10^{-7} \text{ T} \cdot \text{m/A}) (8.00 \times 10^{22} \text{ A} \cdot \text{m}^2)}{4\pi (3.47 \times 10^6 \text{ m})^3} \sqrt{1 + 3(1.00)^2} \\ &= 3.83 \times 10^{-4} \text{ T} . \end{aligned}$$

(c) The angle between the magnetic axis and the rotational axis of the Earth is  $11.5^\circ$ , so  $\lambda_m = 90.0^\circ - 11.5^\circ = 78.5^\circ$  at Earth's geographic north pole. Also  $r = R_e = 6370 \text{ km}$ . Thus,

$$\begin{aligned} B &= \frac{\mu_0 \mu}{4\pi R_E^3} \sqrt{1 + 3 \sin^2 \lambda_m} = \frac{(4\pi \times 10^{-7} \text{ T} \cdot \text{m/A}) (8.0 \times 10^{22} \text{ J/T}) \sqrt{1 + 3 \sin^2 78.5^\circ}}{4\pi (6.37 \times 10^6 \text{ m})^3} \\ &= 6.11 \times 10^{-5} \text{ T} . \end{aligned}$$

(d)  $\phi_i = \tan^{-1}(2 \tan 78.5^\circ) = 84.2^\circ$  .

(e) A plausible explanation to the discrepancy between the calculated and measured values of the Earth's magnetic field is that the formulas we obtained in problem 6 are based on dipole approximation, which does not accurately represent the Earth's actual magnetic field distribution on or near its surface. (Incidentally, the dipole approximation becomes more reliable when we calculate the Earth's magnetic field far from its center.)

74. Let  $R$  be the radius of a capacitor plate and  $r$  be the distance from axis of the capacitor. For points with  $r \leq R$ , the magnitude of the magnetic field is given by

$$B = \frac{\mu_0 \epsilon_0 r}{2} \frac{dE}{dt},$$

and for  $r \geq R$ , it is

$$B = \frac{\mu_0 \epsilon_0 R^2}{2r} \frac{dE}{dt}.$$

The maximum magnetic field occurs at points for which  $r = R$ , and its value is given by either of the formulas above:

$$B_{\max} = \frac{\mu_0 \epsilon_0 R}{2} \frac{dE}{dt}.$$

There are two values of  $r$  for which  $B = B_{\max}/2$ : one less than  $R$  and one greater.

(a) To find the one that is less than  $R$ , we solve

$$\frac{\mu_0 \epsilon_0 r}{2} \frac{dE}{dt} = \frac{\mu_0 \epsilon_0 R}{4} \frac{dE}{dt}$$

for  $r$ . The result is  $r = R/2 = (55.0 \text{ mm})/2 = 27.5 \text{ mm}$ .

(b) To find the one that is greater than  $R$ , we solve

$$\frac{\mu_0 \epsilon_0 R^2}{2r} \frac{dE}{dt} = \frac{\mu_0 \epsilon_0 R}{4} \frac{dE}{dt}$$

for  $r$ . The result is  $r = 2R = 2(55.0 \text{ mm}) = 110 \text{ mm}$ .

75. (a) Since the field lines of a bar magnet point towards its South pole, then the  $\vec{B}$  arrows in one's sketch should point generally towards the left and also towards the central axis.

(b) The sign of  $\vec{B} \cdot d\vec{A}$  for every  $d\vec{A}$  on the side of the paper cylinder is negative.

(c) No, because Gauss' law for magnetism applies to an *enclosed* surface only. In fact, if we include the top and bottom of the cylinder to form an enclosed surface  $S$  then  $\oint_s \vec{B} \cdot d\vec{A} = 0$  will be valid, as the flux through the open end of the cylinder near the magnet is positive.